

# Questionnaire

1. **The illustrative underwater network shown in PART 1 slides contains two kinds of nodes (black and grey). What do the darker black nodes signify ? (*Provide all options that are true*)**

- a. The black nodes illustrate the node with surface expression
- b. The black nodes illustrate the nodes deployed at the bottom of the sea and are accessible only acoustically
- c. The grey nodes illustrate the nodes deployed with surface expression
- d. The grey nodes illustrate the nodes deployed at the bottom of the sea and are accessible only acoustically

2. **What are some of the few dedicated underwater network simulators that exist today ?**

- a. SUNSET
- b. DESERT
- c. UnetSim
- d. All of the above

3. **What functionalities does a physical link layer provide ?**

- a. Modulation and demodulation of signals
- b. Reliability via acknowledgements and retransmissions
- c. None of the above

4. **How are agents in UnetStack different from layers in a traditional network stack ? (*Provide all options that are true*)**

- a. Agents play a similar role as layers in traditional network stacks, but are more flexible in their interaction with other agents
- b. Agents are self-contained independent entities providing a well-defined functionality
- c. None of the above

5. **How are nodes in a simulated underwater network using UnetStack uniquely identified ?**

- a. Node address
- b. Port
- c. IP address of the node over which web interface is accessed
- d. None of the above

6. **What distance apart are the two nodes deployed in the 2 node network simulation demonstrated in PART 1 ?**

- a. 4 km
- b. 1 km
- c. 2 km
- d. 500 m

7. **When a packet is transmitted from a transmitting modem using `phy << new TxFrameReq()` command, what message is received on the receiving modem ?**

- a. `RxFrameNtf` message
- b. `TxFrameNtf` message
- c. `DatagramNtf` message
- d. All of the above

8. To add the agent `EchoDaemon` at the receiving modem, we used the command `container.add 'echo', new EchoDaemon()` on the shell. Provide the command in the space below to add the `EchoDaemon` agent with a different agent name `myechodeamon` .

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9. List down the two general approaches mentioned in PART 3 to add routes to the nodes in the network.

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10. What is the command to check connectivity to a node with address 231 by transmitting 10 packets in UnetStack ?

a. `ping 231`

b. `ping 10, 231`

c. `ping 231, 10`

d. None of the above

11. What pair of nodes shown below do not have a direct connectivity between them in the network shown in PART 3 ?

a. Node 1, Node 2

b. Node 1, Node 3

c. Node 1, Node 4

d. Node 3, Node 4

12. State the reason to add routes on both Node 1 and Node 4 mentioned in PART 3.

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13. What are the node addresses of the nodes on which the routes were added remotely using the `rsh` command in PART 3 ?

a. 1 and 4

b. 1 and 5

c. 4 and 5

d. 3 and 5

14. A code snippet was shown in PART 4 on using UnetSocket API and establish a connection using a particular protocol number `0` as shown here `sock.connect(to, 0)`. What would the equivalent code be for connecting to protocol number `32` ?

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15. What was the command used in PART 4 to enable sensor to start sending data remotely from Node 1 ?

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16. In the second demo of PART 4, what was the protocol that was encapsulated by the UnetStack datagram ?

a. UDP

b. TCP

c. RS232

d. None of the above

17. Define the target node and tracker node mentioned in PART 5.

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18. Which entity is the tracker in PART 5 demonstration of localization ?

a. Python application

b. Beacon node 1

c. Beacon node 2

d. Beacon node 3

**19. What location is the target node deployed at in the network simulated for localization in PART 5 ? (*Mention the 3D coordinate*)**

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**20. Which agent in UnetStack is used for measuring distances to other nodes in the network ?**

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